

MEGA 360 IMAGING



 **HUMMINBIRD**

**Accessory
Manual**

Thank You!

Thank you for choosing Humminbird®, the #1 name in marine electronics. Humminbird has built its reputation by designing and manufacturing top-quality, thoroughly reliable marine equipment. Your Humminbird accessory is designed for trouble-free use in even the harshest marine environment. In the unlikely event that your Humminbird does require repairs, we offer an exclusive Service Policy. For complete details, see the separate warranty card included with your unit. We encourage you to read this manual carefully in order to get the full benefit from all the features and applications of your Humminbird product.



WARNING! This device should not be used as a navigational aid to prevent collision, grounding, boat damage, or personal injury. When the boat is moving, water depth may change too quickly to allow time for you to react. Always operate the boat at very slow speeds if you suspect shallow water or submerged objects.



WARNING! The electronic chart in your Humminbird unit is an aid to navigation designed to facilitate the use of authorized government charts, not to replace them. Only official government charts and notices to mariners contain all of the current information needed for the safety of navigation, and the captain is responsible for their prudent use.



WARNING! Humminbird is not responsible for the loss of data files (waypoints, routes, tracks, groups, recordings, etc.) that may occur due to direct or indirect damage to the unit's hardware or software. It is important to back up your control head's data files periodically. See your control head operations manual for details.



WARNING! Disassembly and repair of this electronic unit should only be performed by authorized service personnel. Any modification of the serial number or attempt to repair the original equipment or accessories by unauthorized individuals will void the warranty.



NOTE: The illustrations in this manual may not look the same as your product, but your unit will function in a similar way.



NOTE: The procedures and features described in this manual are subject to change without notice. This manual was written in English and may have been translated to another language. Humminbird is not responsible for incorrect translations or discrepancies between documents.



NOTE: Product specifications and features are subject to change without notice.



NOTE: Humminbird verifies maximum stated depth in saltwater conditions, however actual depth performance may vary due to transducer installation, water type, thermal layers, bottom composition, and slope.

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Table of Contents

Introduction	1
Compatibility.....	1
Supplies.....	3
Update Software	4
Software Requirements.....	4
Check the Current Software Version	4
Update Control Head Software with an SD Card.....	5
Update Accessory Software with an SD Card	6
Update Software with FishSmart.....	7
Install the Trolling Motor Bracket	8
1. Prepare for Installation	8
2. Install the Trolling Motor Bracket.....	9
A. Ultrex Trolling Motor Mount (MEGA 360 Ultrex)	9
B. Fortrex/Maxxum Trolling Motor Mount (MEGA 360 Fortrex).....	19
3. Route the Cables and Connect Power.....	25
Set Up the Control Head	28
1. Confirm Connections	28
2. Set Up the Transducer.....	30
3. Test MEGA 360 Imaging on the Control Head	31
4. Add Offset Features to the MEGA 360 Imaging Display (optional).....	33
5. Set Up the Network	34
Power Off	35
Maintenance	36
Control Head Maintenance.....	36
Transducer Maintenance	37
MEGA 360 Imaging Maintenance.....	37

Table of Contents

Troubleshooting	38
Fishing System Doesn't Power Up	38
Fishing System Defaults to Simulator with a Transducer Attached	39
Finding the Cause of Noise	40
Specifications	41

Introduction

This manual will guide you through the following installation requirements for the MEGA 360 Imaging transducer:

- Installing the Trolling Motor Bracket
- Connecting to the Control Head and Power
- Testing the Installation
- Powering Off

Before proceeding with this installation, the Humminbird control head and Minn Kota trolling motor should be installed. The MEGA 360 Imaging transducer can be connected directly to the control head or to a Humminbird Ethernet Switch (optional) for networking.

Compatibility

Control Heads: MEGA 360 Imaging is compatible with SOLIX Series and HELIX Series fish finders equipped with MEGA Imaging+ and can be mounted on Minn Kota Ultrex, Fortrex, and Maxxum bow-mount trolling motors.

MEGA 360 Imaging	Minn Kota Trolling Motor	Humminbird Fish Finder
MEGA 360 Ultrex	Minn Kota Ultrex	SOLIX Series: SOLIX G2 models HELIX Series: HELIX MEGA Imaging+ G3N models
MEGA 360 Fortrex	Minn Kota Fortrex Minn Kota Maxxum	SOLIX Series: SOLIX G2 models HELIX Series: HELIX MEGA Imaging+ G3N models



NOTE: You must have a GPS heading sensor (compass) installed in order to use the MEGA 360 Imaging navigation features.



NOTE: MEGA 360 Imaging can be shared with all SOLIX, HELIX G3N, and HELIX G2N models over Ethernet.

Transducers: The MEGA 360 Imaging transducer is compatible with the following transducers:

- HW Dual Spectrum
- HW MEGA DI+
- HW MEGA DI+/MEGA SI+
- Built-in MEGA Imaging transducer on a Minn Kota trolling motor

Cables: Your MEGA 360 Imaging transducer comes with the cables required to connect directly to your Humminbird fish finder. This includes a 10' MEGA 360 power cable, a 10' SOLIX transducer cable, and a 10' HELIX transducer adapter cable.

However, depending on your Humminbird model and system configuration, you may choose to purchase a transducer splitter cable (y-cable) to connect the MEGA 360 to another compatible transducer, as shown below.

MEGA 360 compatible transducer splitter cables (y-cables)	MEGA 360 compatible transducers
MEGA 360 7-pin Transducer Y-cable: 9 M360 2DDI Y (720107-1)	HELIX Dual Spectrum (Type 9 / 7-pin) HELIX MDI+ (Type 9 / 7-pin) HELIX MDI+/MSI+ (Type 9 / 7-pin)
MEGA 360 14-pin Transducer Y-cable: 14 M360 2DDI Y (720108-1)	SOLIX Dual Spectrum SOLIX MDI+ SOLIX MDI+/MSI+ Built-in MEGA Imaging*
*If this cable is being used with a HELIX G3N with MEGA Side or Down Imaging+ and a Built-in MEGA imaging transducer, then the 720109-1 AD HELIX M360 adapter (included with the MEGA 360) must be attached between this y-cable and the HELIX unit.	



NOTE: If a MEGA SI+ transducer is connected with one of these y-cables, the Humminbird unit will not be able to get SI data from the MEGA SI+ transducer – only HW and MEGA DI+ will be available. However, the user can get MEGA SI data from the MEGA 360 transducer.

Accessories: Additional recommended accessories include a Heading Sensor GPS Puck, a Heading Sensor GPS Adapter (SOLIX only), and transducer extension cables.

Supplies

In addition to the hardware included with your accessory, you will need the following supplies:

- Phillips head screwdriver
- Allen wrench
- Hex socket wrench or nut driver
- Cable ties for cable routing
- 1 Amp fuse

Switch (optional): If you do not have a main switch or fuse panel available on your boat to connect power, you will need to purchase a battery switch. See ***Install the Trolling Motor Bracket, Section 3: Route the Cables and Connect Power*** for more information.

Update Software

Your control head model may need a software update to work with the MEGA 360 Imaging transducer. We recommend that you read the following section completely before starting any software updates.

Software Requirements

- SOLIX G2 Series: 3.520 or higher
- HELIX G3N Series: 2.130 or higher

Check the Current Software Version

It is helpful to review the software version number that is currently installed on the control head and each accessory.

SOLIX Series

1. Press the HOME key.
2. Select Settings.
3. Select Network > Network Info.
4. The Network Info dialog box shows a section for each device connected to the network. Scroll to each section to note the software version number listed.

HELIX Series

1. Press and hold the VIEW key.
2. Select System > System Status.
3. Confirm the Software Version listed.

Update Control Head Software with an SD Card

You will need an SD or microSD card (depending on your control head model).



WARNING! Humminbird is not responsible for the loss of data files (waypoints, routes, tracks, groups, snapshots, recordings, etc.) that may occur due to direct or indirect damage to the unit's hardware or software. It is important to back up your control head data files periodically. See your control head operations manual for more information.

1. Before the control head software is updated or restored to system defaults, export your navigation data and copy your screen snapshots to an SD or microSD card. See your control head operations manual for instructions.
2. Install a formatted SD or microSD card into the computer card slot.
3. Go to **humminbird**, and click Support > Software Updates.
4. Click on your control head model. The available software updates are listed as downloads under each product. Confirm the file name is for your control head model.
 - Read the notices and instructions, and select Download.
 - Follow the on-screen prompts to save the software file to the SD or microSD card.
5. Repeat step 4 to download the software updates posted to each product.
6. Insert the SD or microSD card (with the software file) into the control head card slot.
7. Power on your Humminbird control head. Start **Normal** mode.
8. Follow the on-screen prompts to update the control head software.
9. When the software update is complete, remove the SD or microSD card from the control head card slot.
10. **Restart:** If you don't have any other software updates to install, power off the control head, and restart it.

Update Accessory Software with an SD Card

You will need an SD or microSD card (depending on your control head model).

1. Install a formatted SD or microSD card into the computer card slot.
2. Go to **humminbird**, and click Support > Software Updates.
3. Scroll down to Accessories and Mapping. The available software updates are listed as downloads under each accessory product. Confirm your control head model is listed in the software description.
 - Read the notices and instructions, and select Download.
 - Follow the on-screen prompts to save the software file to the SD or microSD card.
4. Insert the SD or microSD card (with the software file) into the control head card slot.
5. Power on your Humminbird control head. Start **Normal** mode.
6. The software will be updated automatically. It may take up to two minutes for the software to be detected on the network, and the control head will display a dialog box to indicate that the update is in progress.
7. When the software update is complete, remove the SD or microSD card from the control head card slot.
8. **Restart:** If you don't have any other software updates to install, power off the control head, and restart it.

Update Software with FishSmart

You can use the FishSmart App to download and push software updates directly to your Humminbird control head or accessory.



NOTE: Your control head must already be running software release 1.610 or higher for HELIX Series or 3.110 or higher for SOLIX Series to support this feature.



NOTE: You must first download the FishSmart App and pair your mobile device to your control head. See the *FishSmart User Manual* for more information.

1. Open the FishSmart App on your mobile device.
2. **Apple iOS:** Tap the System menu icon.
Google Android: Tap the FishSmart main menu. Select system.
3. Tap Update next to the selected unit. The download progress is displayed on the screen.
4. Tap Transfer next to the selected unit once the download is complete.
5. Confirm the estimated transfer time.
6. Tap the checkbox to select where to upload the software update (internal storage, card slot 1, or card slot 2).



NOTE: For SOLIX Series control heads, you cannot download software updates to an SD or microSD card with LakeMaster charts saved to it.

7. Tap Transfer. The upload progress is displayed on the System menu in FishSmart and in the System Status view on the control head.
8. Follow the on-screen prompts on the control head to complete the software installation.

Install the Trolling Motor Bracket

Use the following instructions to install the MEGA 360 Imaging transducer on your Minn Kota trolling motor. It is important to read the instructions completely and understand the mounting guidelines before you start the installation.

1. Prepare for Installation

1. Disconnect the motor from all sources of electrical power.
2. Test run the transducer cable from the chosen mounting location on the trolling motor to the control head. Test run the power cable from the chosen mounting location on the trolling motor to the main switch or fuse panel.

It is important to consider the following:

- The MEGA 360 Imaging transducer pod is powered separately from the control head. It must be connected to a switch where it can be powered on when the boat is underway and powered off when it is docked.
 - The cables should be routed through an established routing system on the boat, in an area with minimal interference, without sharp edges, obstacles, or obstructions that may damage the cables.
 - The cables will move with the trolling motor when it is deployed and retracted, so it is important to allow enough length for movement.
3. With the trolling motor deployed, the transducer pod has the following installation requirements:
 - The transducer pod should not have anything obstructing the 'view' of the rotating beams (besides the trolling motor and shaft). If possible, move anything to the sides and below the pod that might obstruct the sight line of the rotating beams.
 - The pod must be mounted at least 1" (25.4 mm) off the tip of the propeller.
 - **MEGA 360 Ultrex:** The pod should be submerged 6" (152.4 mm) below the waterline. The height may be adjusted, however, the pod must be mounted 1" (25.4 mm) off the tip of the propeller.

2. Install the Trolling Motor Bracket


Proceed to the installation section of the type of trolling motor bracket you purchased:


A. Ultrex Trolling Motor Mount (MEGA 360 Ultrex)

OR

B. Fortrex/Maxxum Trolling Motor Mount (MEGA 360 Fortrex)

A. Ultrex Trolling Motor Mount (MEGA 360 Ultrex)

 **WARNING!** Disconnect the motor from all sources of electrical power before you start installation.

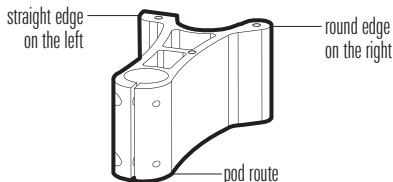
 **WARNING!** Confirm that the trolling motor is properly secured to the boat and will not shift during the installation.

Assemble the Bracket

1. The trolling motor should be in the fully retracted (flat) position on the boat deck for this installation.
2. Disconnect the motor from all sources of electrical power.
3. In addition to the requirements listed in the *Prepare for Installation* section, determine if the bracket will be installed on the left or right side of the trolling motor, so the transducer pod is mounted outboard of the trolling motor and on the centerline of the boat. Determine the mount position from the bow, facing the (forward) direction of travel.

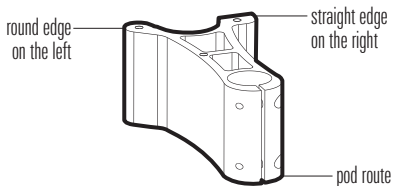
If the trolling motor deploys starboard side (right) on the bow, you will mount the bracket on the left side of the trolling motor. Position the bracket so the straight edge faces to the left as shown in the illustration.

Positioning the Bracket for Installation on the Left Side of Trolling Motor



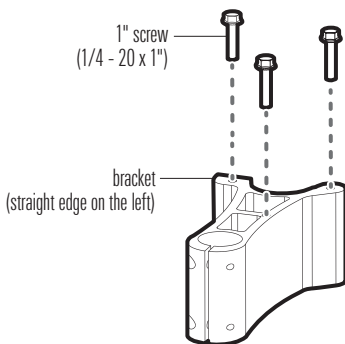
If the trolling motor deploys port side (left) on the bow, you will mount the bracket on the right side of the trolling motor. Position the bracket so the straight edge faces to the right as shown in the illustration.

Positioning the Bracket for Installation on the Right Side of Trolling Motor



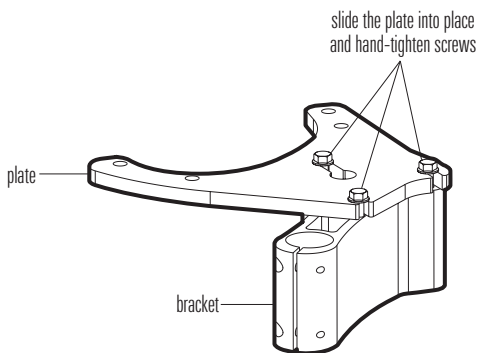
4. Install the (3) 1/4-20 x 1" screws into the threaded holes on the bracket as shown in the illustration. Do not fully tighten.

Installing the Screws onto the Bracket



- Align the center hole of the plate over the left screw (left side installation) or right screw (right side installation).
- Lower the plate onto the screw head, and slide the screw into the plate slot. Slide the other two screws into the outside slots on the plate. If the plate does not slide easily into place, flip it over.

Securing the Plate and Bracket

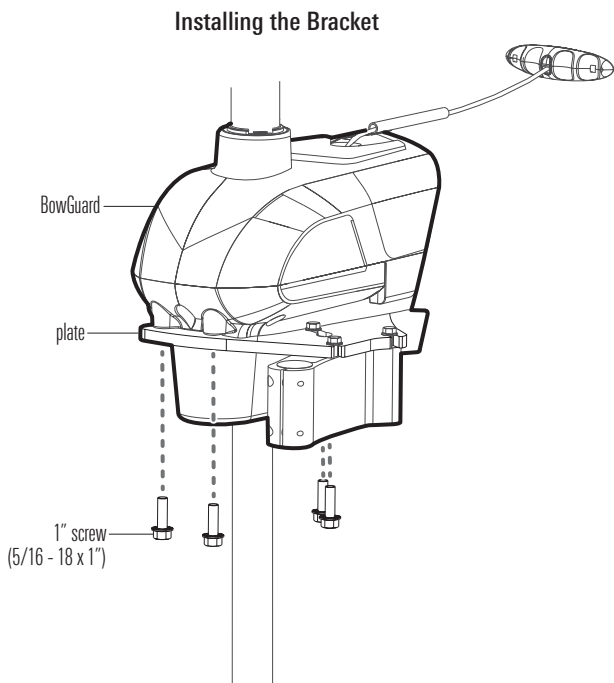


- Hand-tighten the screws using a 1/4" nut driver or socket wrench. **Hand-tighten only!**

Install the Bracket

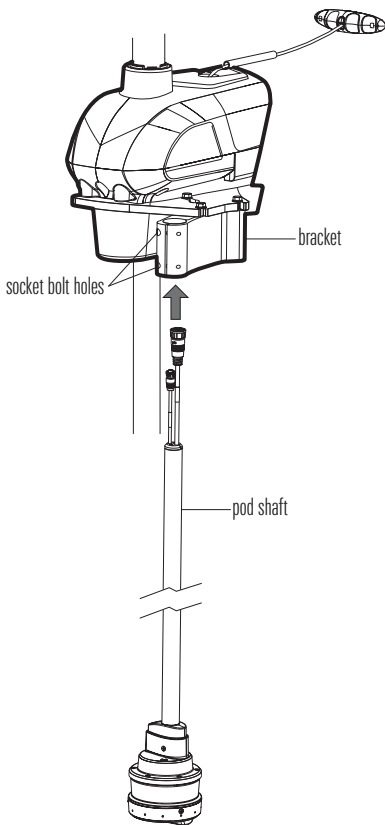
As determined in the *Assemble the Bracket* section, the bracket can be mounted on the left or right side of the trolling motor.

1. Align the plate below the BowGuard. Line up the holes on the plate with the threaded holes on the BowGuard.
2. Install the (4) 5/16-18 x 1" screws through the plate and into the BowGuard. Hand-tighten using a 5/16 nut driver until secure (see the illustration *Installing the Bracket*). **Hand-tighten only!**



3. Route the cables and pod shaft up through the trolling motor bracket.
4. Use an Allen wrench (not included) to install the (2) 10-32 x 9/16" socket bolts on the bracket where the pod shaft is installed.
5. Tighten the bolts so the pod shaft is fully secure and won't drop when it is deployed in the next step. **Hand-tighten only!**

Routing the Cables and Pod Shaft



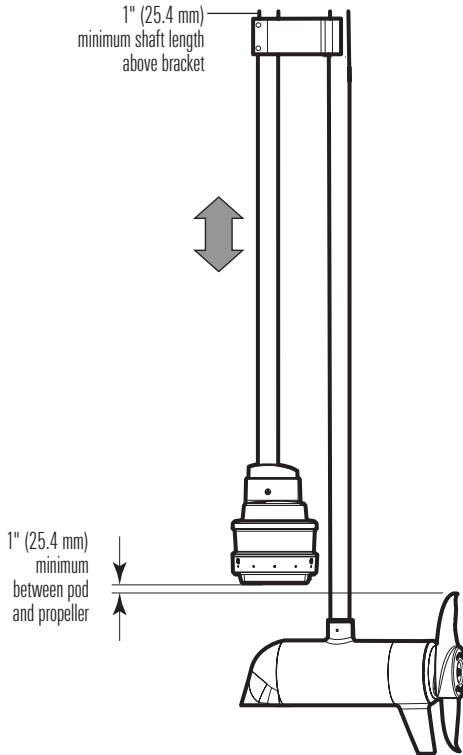
Adjust the Pod Height

1. Deploy the Trolling Motor.
2. Loosen the socket bolts on the bracket where the pod shaft is installed. Adjust the pod shaft up or down, so it meets the following height requirements:
 - The pod must be mounted approximately 6" (152.4 mm) below the waterline.
 - The pod must be mounted at least 1" (25.4 mm) off the tip of the propeller.
 - The pod shaft needs to protrude at least 1" to 2" (25.4 mm to 50.8 mm) above the bracket when it is installed.



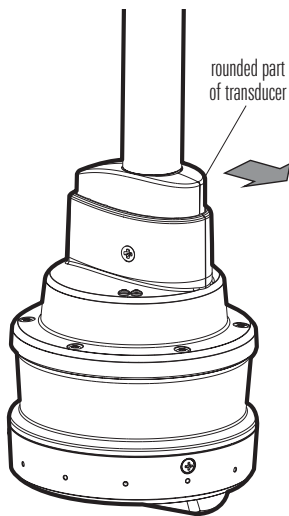
WARNING! Do not install the pod too close to the propeller. If the pod is installed too close to the propeller, it will be damaged.

Adjusting the Pod Height (at least 1" from the tip of the propeller)



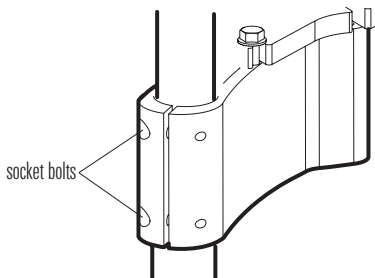
3. Turn the pod shaft until the rounded end of the transducer points in the direction of travel. The centerline of the transducer should be parallel with the centerline of the boat. See the illustration *Aligning the Transducer*.

Aligning the Transducer



4. When the transducer position is finalized, hand-tighten the socket bolts equally and completely so the pod shaft is fully secure and won't drop or rotate during operation. Tighten each bolt an additional 1/4 or 1/2 turn. **Hand-tighten only!**

Hand-Tightening the Socket Bolts

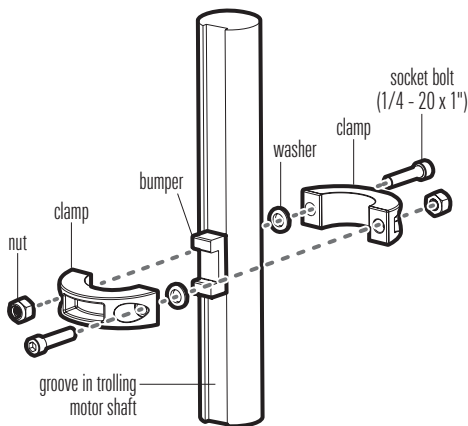


Install the Collar Clamp

After you have established the pod height is no closer than 1 inch from the tip of the propeller, install the collar clamp to prevent the trolling motor from hitting the transducer pod.

1. Apply anti-seize to the end of each 1" socket bolt (1/4-20 x 1").
2. Install a 1" socket bolt (1/4-20 x 1") into the hole on 1 clamp half.
3. Place the bumper into the groove of the trolling motor shaft. Center one clamp half over the bumper as shown in the illustration.
4. Install a washer, the clamp (half), and hex nut (1/4-20) onto the trolling motor shaft as shown in the illustration. Repeat on the other side.

Installing the Collar Clamp



NOTE: If your installation kit does not include a washer, you may skip the washer portion of the installation.


5. Use an Allen wrench (not included) to tighten the hardware just enough to keep the collar assembled.
6. Slide the collar up to the base of the BowGuard.
7. Use an Allen wrench (not included) to fully tighten the socket bolts until they are secure. **Hand-tighten only!**


Details: Tighten the socket bolts and collar clamp hardware evenly on both sides of the clamp until you feel them start to compress and secure, and then tighten each bolt an additional 1/4 to 1/2 turn.



WARNING! The socket bolts must be tightened completely to prevent the trolling motor from potentially damaging the pod. **Hand-tighten only!**

B. Fortrex/Maxxum Trolling Motor Mount (MEGA 360 Fortrex)

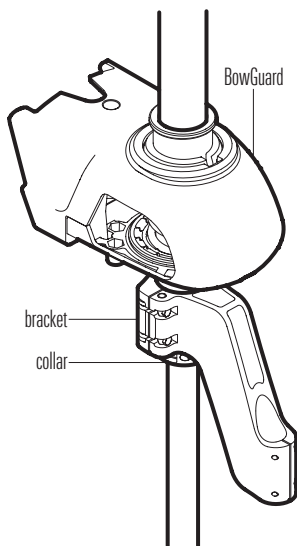
 **WARNING!** Disconnect the motor from all sources of electrical power before you start installation.

 **WARNING!** Confirm that the trolling motor is properly secured to the boat and will not shift during the installation.

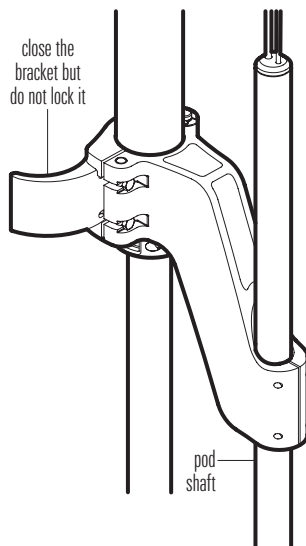
The trolling motor should be in the fully retracted (flat) position on the boat deck for this installation.

1. Align the bracket below the BowGuard and slightly above the collar. Close the bracket, but do NOT lock it.
2. Route the cables and pod shaft up through the smaller hole on the trolling motor bracket.

Aligning the Bracket



Routing the Cables and Pod Shaft



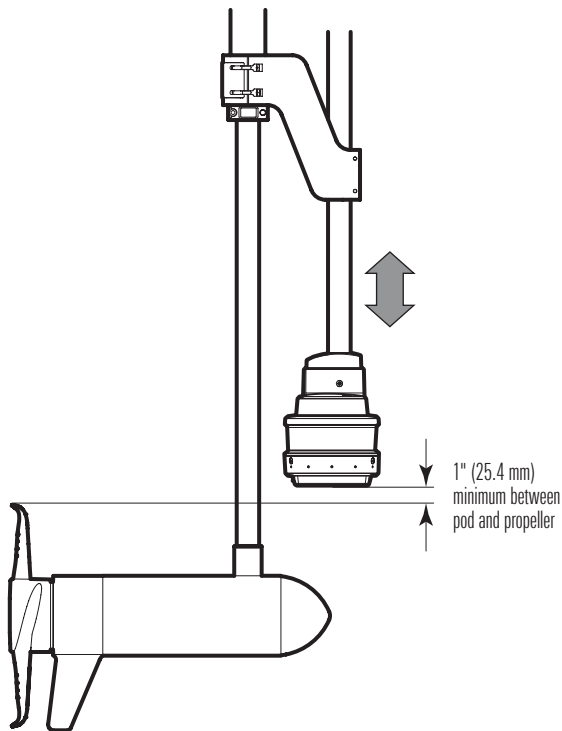
- Adjust the pod shaft up or down, so the pod is at least 1" (25.4 mm) off the tip of the propeller.



WARNING! DO NOT INSTALL THE POD TOO CLOSE TO THE PROPELLER.

If the pod is installed too close to the propeller, it will be damaged.

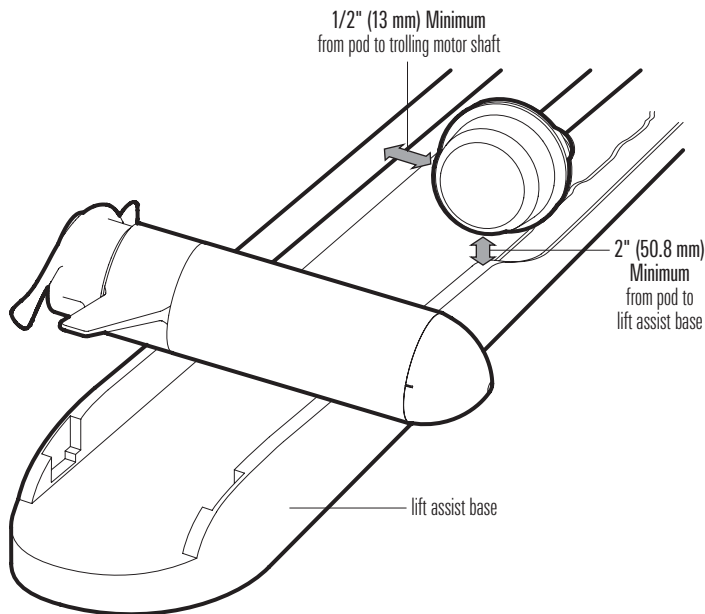
Adjusting the Pod Height (at least 1" from the tip of the propeller)



- Pivot the bracket until the pod is at least 2" (50.8 mm) from the lift assist base and at least 1/2" (13 mm) from the trolling motor shaft. See the illustration *Measuring the Safety Distance of the Pod and Positioning the Bracket*.

⚠ WARNING! The pod must not hit the trolling motor shaft, lift assist base, or any objects. These measurements are also critical during transport when the pod is stowed with the trolling motor.

Measuring the Safety Distance of the Pod



- Close the bracket lock.

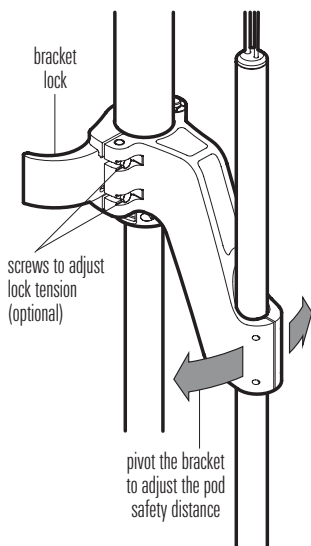
🔧 NOTE: For a secure installation, it should take significant force to lock down the bracket. The bracket lock can be tightened by adjusting the tightness of the screws (see the illustration *Positioning the Bracket*). If you adjust the screws, make sure you adjust each screw equally.

- Use an Allen wrench (not included) to install the (2) 10-32 x 5/8" hex socket bolts on the bracket where the pod shaft is installed (see the illustration **Securing the Pod**).

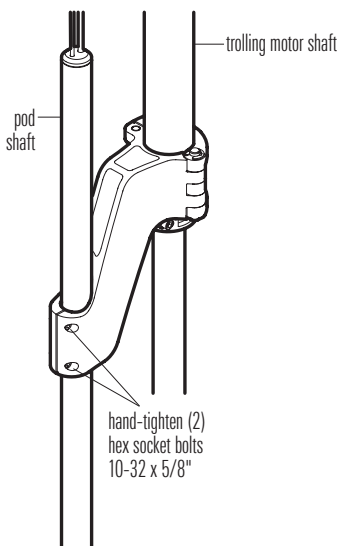
Tighten the bolts so the pod shaft is fully secure and won't drop when it is deployed in the next step. Hand-tighten only!

- Deploy the Trolling Motor.

Positioning the Bracket



Securing the Pod



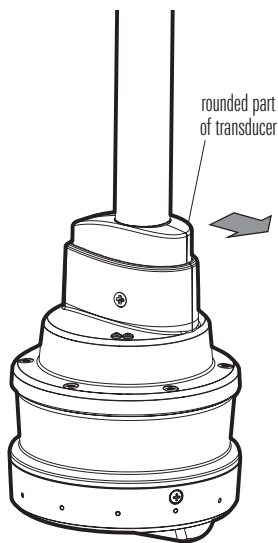
- Turn the pod shaft until the rounded end of the transducer points in the direction of travel. The centerline of the transducer should be parallel with the centerline of the boat. See the illustration *Aligning the Transducer*.



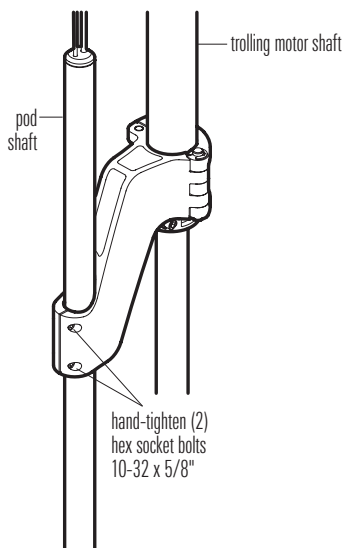
NOTE: You might need to loosen the hex socket bolts to adjust the transducer alignment.

- When the transducer position is finalized, hand-tighten the hex socket bolts completely so the pod shaft is fully secure and won't drop or rotate during operation. **Hand-tighten only!**

Aligning the Transducer



Confirming the Pod is Secure



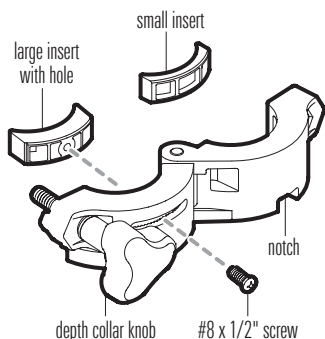
- Above the BowGuard, unscrew the Depth Collar Knob to remove the clamp.

11. Install the large insert into the slotted side of the clamp. Use a Phillips screwdriver to install the #8-1/2" screw through the clamp and large insert (see the illustration *Installing the Inserts*).
12. Install the small insert into the solid side of the clamp. Hold it in place, and re-install the clamp and Depth Collar Knob. Make sure the clamp notch is facing down and fits onto the collar node (see the illustrations *Installing the Inserts* and *Re-installing the Depth Collar Knob*).
13. Fully hand-tighten the Depth Collar Knob.

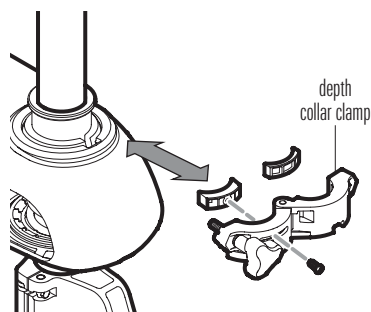


WARNING! The Depth Collar knob must be tightened fully to prevent the bracket from rotating and potentially damaging the pod. **Hand-tighten only!**


Installing the Inserts



Re-installing the Depth Collar Knob



3. Route the Cables and Connect Power

 **WARNING!** The power source must be turned off before you proceed with this installation.

1. Connect the power cable to the power cable connector on the pod shaft, and connect the transducer cable to the transducer cable connector on the pod shaft.

The connectors are keyed to prevent reversed installation, so be careful not to force the connectors. Hand-tighten the screw nuts on each connector.



NOTE: If you are connecting the MEGA 360 Imaging transducer and another compatible transducer to the same control head, you will need to purchase a transducer splitter cable (y-cable).

2. Route the cables to the side of the trolling motor, over the bow, to the chosen connection locations in ***Section 1: Prepare for Installation***. Leave sufficient slack in the cables to allow for full movement of the trolling motor during normal operation.



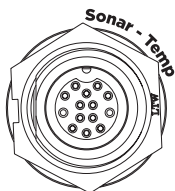
CAUTION! Do NOT mount the cables where the connectors could be submerged in water or flooded. If cables are installed in a splash-prone area, it may be helpful to apply dielectric grease to the inside of the connectors to prevent corrosion. Dielectric grease can be purchased separately from a general hardware or automotive store.



NOTE: The cables should be routed through an established routing system on the boat, in an area with minimal interference. Inspect the selected route carefully to ensure that there are no sharp edges, obstacles, or obstructions that may damage the cables.

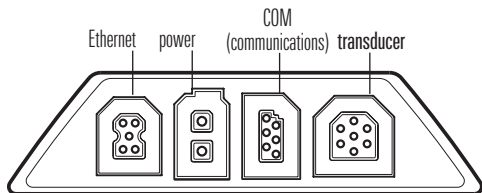
3. **SOLIX:** Insert the other end of the transducer cable to the sonar port on the control head. Hand-tighten the screw nut.

SOLIX Sonar-Temp Port

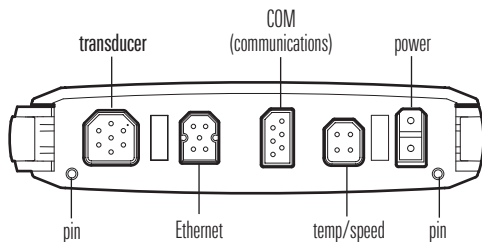


- HELIX:** Insert the transducer adapter cable to the transducer port on the HELIX control head.

HELIX 7 Control Head Ports



HELIX 8, 9, 10, 12 Cable Tray



4. **Power:** Route the power cable to the main switch or fuse panel (usually located near the console). If you must connect to a battery, connect to a battery switch (not included).



WARNING! The MEGA 360 Imaging transducer should be connected to a main switch, fuse panel, or battery switch. Humminbird does not recommend connecting to a battery without a fuse and a switch.



CAUTION! Some boats have 24 or 36 Volt electric systems, but the MEGA 360 Imaging transducer **MUST** be connected to a 12 VDC power supply.



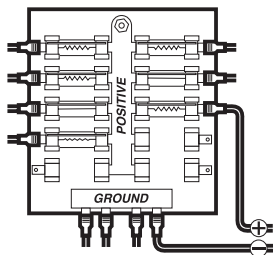
NOTE: A 10' (3 m) power cable is included to supply power to the MEGA 360 Imaging transducer. You may shorten or lengthen the cable using 18 gauge multi-stranded copper wire.



NOTE: Humminbird is not responsible for over-voltage or over-current failures. The MEGA 360 Imaging transducer must have adequate protection through the proper selection and installation of a 1 Amp fuse.

- 5a. **Main Switch/Fuse Panel:** If a fuse terminal is available, use crimp-on type electrical connectors (not included) that match the terminal on the fuse panel. Attach the black wire to ground (-), and the red wire to positive (+) 12 VDC power. Install a 1 Amp fuse (not included) for protection of the unit.

Connecting to the Fuse Panel



OR

- 5b. **Battery Switch:** Install the battery switch (not included) using the instructions provided with it. You will also need to obtain and install an inline fuse holder and a 1 Amp fuse (not included) for the protection of the unit. Attach the black wire to ground (-), the red wire to positive (+) 12 VDC power, and the shield wire to the boat's chassis ground terminal.



WARNING! If you are unable to obtain a battery switch and are forced to connect the power cable directly to the battery, be aware that this will drain the battery. Humminbird does not recommend connecting to a battery without the appropriate fuse and a switch.


6. Tape the drain wire.

7. Secure the cables with cable ties along the route as needed for a clean assembly.

Set Up the Control Head

When the control head detects the MEGA 360 Imaging transducer, it will select it automatically as the 360 sonar source. The related views and menus will be added to the system.





Use the following instructions to power on the control head and confirm the MEGA 360 Imaging transducer is detected by the unit.

 **CAUTION!** It is important to finish all installation connections before powering on the control head.

1. Confirm Connections

SOLIX Series

1. Turn on the power source from the main switch.
2. On the control head, press and hold the POWER key. **If you are powering on a control head in a multiple-control head Ethernet network**, power on the control head that is connected to the MEGA 360 Imaging transducer first.
3. Select Normal mode.
4. Review the status bar in the top, right corner of the screen to confirm the sensor status for the MEGA 360 Imaging transducer is connected.

MEGA 360 Status Icon	Icon Description
	Connected/In Water/Pinging: The MEGA 360 is connected, in the water, and pinging.
	Connected/In Water/Not Pinging: The MEGA 360 is connected and in the water, but it is not pinging.
	Connected/Out of Water: The MEGA 360 is connected, but the wet indicator is out of the water.
	Connection Lost: The connection to the MEGA 360 was lost.



NOTE: For additional system status, select Home > Settings > Network > System Info.

MEGA 360 Imaging Transducer Connected (SOLIX)

The screenshot shows the 'System Info' screen in the SOLIX interface. The 'Network' section is highlighted in the left sidebar. The 'MEGA 360' transducer is listed as 'Connected'. Annotations with arrows point to the 'MEGA 360' icon in the status bar and the 'MEGA 360 Imaging listed as transducer' text.

Item	Value	Item	Value
Module	SOLIX 12 HSH 4 G2	Serial Number	190716030180
Unit Name	190716030180	IP Address	10.11.2.38.31
Software Version	3.5200/3Q19 17.21	MAC Address	2C:40:7D:E1:81:54
Network Name	NET-190716030180		
Internal GPS	Flu		
IMEA 0183 (1)	GPS, Hdg, Pitch and Roll		
IMEA 0183 (2)			
IMEA 2000	Not Connected		
Transducer	2D/DO/3E/MEGA_360		
MEGA 360	V3.030.50H 19082901 - 1010		
Sonar Temp	Connected		
Speed (Paddle Wheel)	Not Connected		
Aux Temp	Not Connected		
Master Unit	---		

HELIX Series

1. Turn on the power source from the main switch.
2. On the control head, press the POWER key. **If you are powering on a control head in a multiple-control head Ethernet network**, power on the control head that is connected to the MEGA 360 Imaging transducer first.
3. When the Title screen is displayed, press the MENU key.
4. Select Normal. Press the RIGHT Cursor key.
5. Press and hold the VIEW key. Select System > Accessory Test. Confirm that **MEGA 360 Imaging** is listed as Connected.



NOTE: If the Accessory Test is not displayed in the View Rotation, press the MENU key twice to open the Main Menu. Select the Views tab > Accessory Test. Change the setting to Visible.

HELIX Accessory Test

		Accessory Test	
		360 Imaging	UNCONNECTED
		BT Talon	UNCONNECTED
Temp.1 °F	72.2	GPS	CONNECTED
		i-Pilot	UNCONNECTED
N 34°06.248'		MEGA 360 Imaging vL040 S/N: 19082901-0072	CONNECTED
W 084°12.385'		NMEA2K Gateway	UNCONNECTED
		Radar	UNCONNECTED
Time	7:01	Remote	UNCONNECTED
		Speed	UNCONNECTED
Speed mph	0.2	Temperature	CONNECTED
VLT IV	13.4		

MEGA 360 Imaging listed as Connected

2. Set Up the Transducer

SOLIX Series

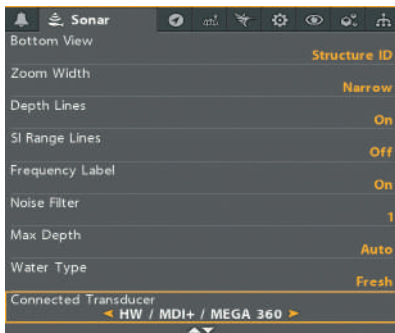
Your SOLIX control head will automatically detect the connected transducers. To review the selected sonar sources, open the Settings tool, and select CHIRP Sonar > Sonar Source.

HELIX Series

Use the following instructions to select the connected transducer for your control head. These steps are only required the first time you set up your HELIX control head with a new transducer.

1. **Main Menu:** Press the Menu key twice.
2. Select the Sonar tab > Connected Transducer.
3. Press the RIGHT or LEFT Cursor keys to scroll through the compatible transducers. Select the transducer that is attached to the control head.

Selecting the Connected Transducer (HELIX)



3. Test MEGA 360 Imaging on the Control Head

It is important to confirm that the MEGA 360 Imaging transducer is providing sonar returns to the display. The instructions in this section should be performed at trolling speeds in calm, open water, in a large area that is far from shallow water, boats, or other obstacles.

WARNING! The pod should NOT be in the water during high speed travel. The pod should only be deployed when the boat is traveling at trolling speeds.

SOLIX Series

1. Tap the View widget icon in the side bar.

NOTE: Once the MEGA 360 has been detected the first time, the 360 Imaging view will display on the Favorite Views widget.

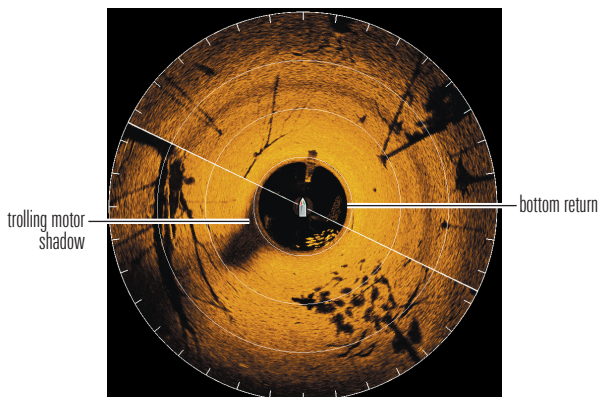
2. Tap 360 Imaging.
3. The sonar returns from the MEGA 360 scan will begin to display on the MEGA 360 View. Review the display for the following information and see the illustration *Reviewing the 360 View*.
 - **Bottom:** Confirm that the bottom is visible on-screen.
 - **Blocked Beams:** If the beams hit a hard surface, it will appear as bright white on the display. If the beams are blocked by any objects, move the objects if possible. You can also adjust the 360 Range on the X-Press Menu to see more or less detail on the display. In some cases, the trolling motor will appear on the display as a shadow.

4. **Stop Pinging:** When you are finished reviewing the operation, tap Ping Off from the 360 status bar.

HELIX Series

1. Press and hold the VIEW key.
2. Select Sonar > 360 View.
3. The sonar returns from the MEGA 360 scan will begin to display on the MEGA 360 View. Review the display for the following information and see the illustration *Reviewing the 360 View*.
 - **Bottom:** Confirm that the bottom is visible on-screen.
 - **Blocked Beams:** If the beams hit a hard surface, it will appear as bright white on the display. If the beams are blocked by any objects, move the objects if possible. You can also adjust the 360 Range on the X-Press Menu to see more or less detail on the display. In some cases, the trolling motor will appear on the display as a shadow.
4. **Stop Pinging:** When you are finished reviewing the operation, press the MENU key once. Select 360 Pinging, and press the LEFT Cursor key.

Reviewing the 360 View



4. Add Offset Features to the MEGA 360 Imaging Display (optional)

The menu settings in this section are helpful for interpreting the position of objects on the 360 View. This feature is only available with a connected heading sensor (compass).

Adjust the 360 Heading Offset

If the positions of objects on the MEGA 360 Imaging display are slightly different than what you observe in the environment around you, use 360 Heading Offset to correct the alignment of the MEGA 360 Imaging display.

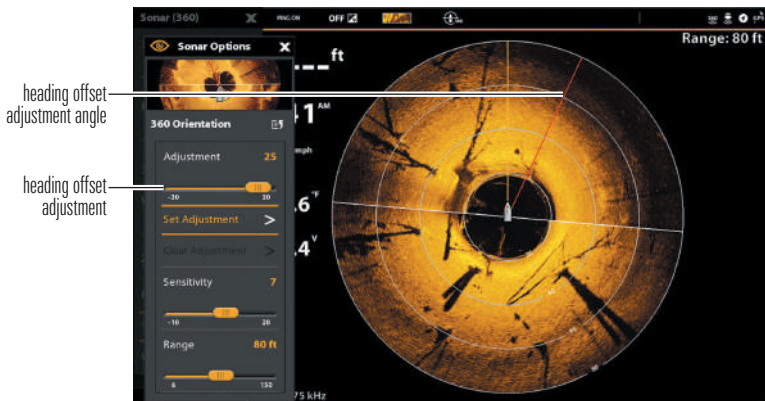
For example, if there is an object in the water that is displayed on the left side of the MEGA 360 View, but you can see that it is straight ahead, you can use this setting to rotate the display.

 **NOTE:** This menu option should be adjusted while the MEGA 360 Imaging transducer is pinging.

SOLIX Series

1. With a MEGA 360 View displayed on-screen, tap Sonar (360) in the status bar or press the MENU key once.
2. Select Sonar Options > Preferences > 360 Orientation.
3. Press and hold the slider under Adjustment to change the angle (red line).

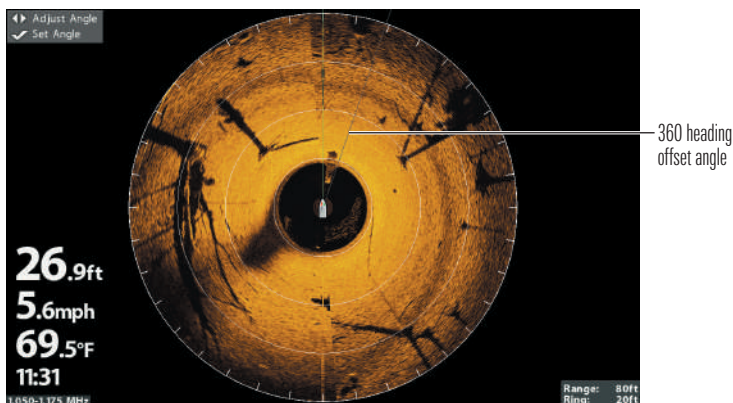
MEGA 360 Imaging Heading Offset (SOLIX)



HELIX Series

1. **Main Menu:** Press the MENU key twice.
2. Select the Accessories tab > MEGA 360 Settings > 360 Heading Offset.
3. Press the RIGHT or LEFT Cursor keys to change the angle (gray line), and press the CHECK/INFO key to confirm your setting. The zero point on the display is represented by a green line.


MEGA 360 Imaging Heading Offset (HELIX)



5. Set up the Network

After you have confirmed all connections, the MEGA 360 Imaging transducer is ready to use on the water. Proceed to your *MEGA 360 Operations Manual* to set up the depth source, temperature source, and additional sonar sources.


Power Off

 **WARNING!** When the boat is stored or at dock, the MEGA 360 Imaging transducer must be turned off to prevent draining the battery.

Power Off the Control Head

1. **SOLIX Series:** During operation, tap the top, right corner of the status bar or press the POWER key, and select Power Off.

HELIX Series: Press and hold the POWER key.

 **CAUTION!** Turning off the control head will NOT power off the MEGA 360 Imaging transducer.

2. Turn off power on the main switch, breaker, or battery switch.

Powering off the MEGA 360 Imaging transducer will be determined by the installation and power connection on your boat.

Travel with the Pod Installed

1. Confirm the Depth Collar Knob is fully tightened (by hand).
2. The pod must not hit the trolling motor shaft, base, or any objects. This is also critical during transport or when the trolling motor is stowed. Check the stability of the trolling motor bracket after initial use and periodically thereafter to ensure that the installation and lock remain stable.

For measurement requirements, see Install the *Trolling Motor Bracket*.

Maintenance

Your Humminbird fishfinder is designed to provide years of trouble free operation with very little maintenance. Use the following procedures to ensure your Humminbird continues to deliver top performance.

Control Head Maintenance

It is important to consider the following precautions when using your Humminbird control head:

- **Chemicals**, such as those found in bug spray and sunscreen, may cause permanent damage to the control head screen. Such damage is not covered by the warranty.
- **NEVER leave the control head in a closed car or trunk.** The high temperatures generated in hot weather can damage the electronics.

Use the following information to keep the control head and screen clean.

- **Screen:** To clean the control head screen, use a mild soap (such as a nonabrasive liquid hand soap) and warm water. Wipe the screen dry with a soft cloth. Be careful to avoid scratching the screen. If water spots remain, use a solution of water and vinegar.



WARNING! Do not use a chemical glass cleaner on the screen. Chemicals in the solution may cause cracking in the lens of the unit.



NOTE: Do not wipe the screen while dirt or grease is on the screen.

- **Control Head:** If the control head comes into contact with salt spray, wipe the affected surfaces with a cloth dampened with fresh water.

Transducer Maintenance

Use the following information to maintain the transducer operation.

- If your boat remains in the water for long periods of time, algae and other marine growth can reduce the effectiveness of the transducer. Periodically clean the face of the transducer with a cloth dampened with fresh water.
- If your boat remains out of the water for a long period of time, it may take some time to wet the transducer when it is returned to the water. Small air bubbles can climb to the surface of the transducer and interfere with proper operation. These bubbles dissipate with time, or you can wipe the face of the transducer with your fingers after the transducer is in the water.

MEGA 360 Imaging Maintenance

Use the following information to maintain the installation of the MEGA 360 Imaging Transducer.

- Check the stability of the trolling motor bracket after initial use and periodically thereafter to ensure that the installation and lock remain stable.
- If your boat will be in long-term storage, remove the MEGA 360 Imaging pod shaft from the bracket and store it in -40°F to 158°F (-40°C to 70°C), dry conditions.

Troubleshooting

Before contacting the Humminbird Technical Support, please read the following section. Taking the time to review these troubleshooting guidelines may allow you to solve a performance problem yourself, and therefore avoid sending your unit back for repair.

Fishing System Doesn't Power Up

If your Fishing System doesn't power up, use the installation guide that is included with your Fishing System to confirm specific details, making sure that:

- the power cable is properly connected to the Fishing System control head,
- the power cable is wired correctly, with red to positive battery terminal and black to negative terminal or ground,
- the fuse is operational, and
- the battery voltage of the power connector is at least 12 Volts.

Correct any known problems, including removing corrosion from the battery terminals or wiring, or actually replacing the battery if necessary.

Fishing System Defaults to Simulator with a Transducer Attached

In addition to the MEGA 360 Imaging accessory transducer, you will have a standard Humminbird transducer connected to the control head. A connected and functioning transducer with built-in temperature will cause the newly-started Fishing System to go into Normal operating mode automatically. If, when you power up the Fishing System, it goes into Simulator mode automatically, even though a transducer is already connected, this means that the control head is not detecting the transducer. Perform the following troubleshooting tasks:

- Check the connections of all transducers that are connected to the control head or Ethernet network. See the transducer installation guide that was included with your Fishing System for connection information.
- Review this MEGA 360 Imaging installation guide to confirm that the transducer cable is connected correctly to the Fishing System. Reconnect if necessary, and power on the Fishing System again to see if this fixes the problem.
- Replace the non-functioning transducer with a known good transducer if available and power up the control head again.
- Check the transducer cable. Replace the transducer if the cable is damaged or corroded.

Finding the Cause of Noise

Electrical noise usually affects the display with streaks or repetitive patterns on the view. One or more of the following sources can cause noise or interference:

Possible Source of Noise	Isolation
Other electronic devices	Turn off any nearby electronic devices to see if the problem goes away, then turn them on one at a time to see if the noise re-appears.
Other sonar devices	Turn off any nearby sonar devices to see if the problem goes away, then turn them on one at a time to see if the noise re-appears.
The boat's engine	To determine whether the boat's engine is the source of the noise, increase the RPMs while the boat is in neutral and stationary to see if the noise increases proportionately; if noise appears when you rev the engine, the problem could be the spark plugs, alternator, or tachometer wiring. Replace the spark plugs with resistor plugs, install an alternator filter, or route the control head power and transducer cables away from the engine wiring.

Specifications

Operating Frequency.....	455 kHz / MEGA
Area of Coverage	455 kHz / MEGA: (2) 90° @ -10 dB
Power Output.....	500 Watts (RMS), 4000 Watts (Peak to Peak)
Power Requirement	10 to 18 VDC
Current Draw5 A maximum
Operating Temperature.....	-4°F to 158°F (-20°C to 70°C)
Storage Temperature	-40°F to 158°F (-40°C to 70°C)



NOTE: Humminbird verifies maximum stated depth in saltwater conditions, but actual depth performance may vary due to transducer installation, water type, thermal layers, bottom composition and slope.



NOTE: Product specifications and features are subject to change without notice.

ROHS STATEMENT: Product designed and intended as a fixed installation or part of a system in a vessel may be considered beyond the scope of Directive 2002/95/EC of the European Parliament and of the Council of 27 January 2003 on the restriction of the use of certain hazardous substances in electrical and electronic equipment.

ENVIRONMENTAL COMPLIANCE STATEMENT: It is the intention of Johnson Outdoors Marine Electronics, Inc. to be a responsible corporate citizen, operating in compliance with known and applicable environmental regulations, and a good neighbor in the communities where we make or sell our products.

WEEE DIRECTIVE: EU Directive 2002/96/EC “Waste of Electrical and Electronic Equipment Directive (WEEE)” impacts most distributors, sellers, and manufacturers of consumer electronics in the European Union. The WEEE Directive requires the producer of consumer electronics to take responsibility for the management of waste from their products to achieve environmentally responsible disposal during the product life cycle.

WEEE compliance may not be required in your location for electrical & electronic equipment (EEE), nor may it be required for EEE designed and intended as fixed or temporary installation in transportation vehicles such as automobiles, aircraft, and boats. In some European Union member states, these vehicles are considered outside of the scope of the Directive, and EEE for those applications can be considered excluded from the WEEE Directive requirement.



This symbol (WEEE wheelie bin) on product indicates the product must not be disposed of with other household refuse. It must be disposed of and collected for recycling and recovery of waste EEE. Johnson Outdoors Marine Electronics, Inc. will mark all EEE products in accordance with the WEEE Directive. It is our goal to comply in the collection, treatment, recovery, and environmentally sound disposal of those products; however, these requirements do vary within European Union member states. For more information about where you should dispose of your waste equipment for recycling and recovery and/or your European Union member state requirements, please contact your dealer or distributor from which your product was purchased.

Learn more about marine electronics and navigation we have.